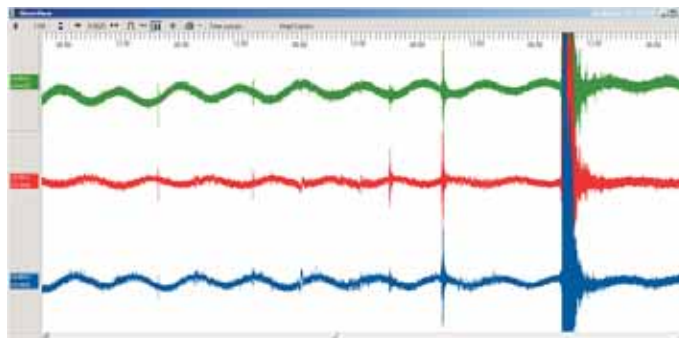


- Covers the complete seismic spectrum up to 50 Hz, and a single transfer function defines the sensor response. (100Hz high frequency corner option)
- Suitable for local, regional and teleseismic recording.
- Truly portable seismometer with a lifting handle and easy access to electric connection.
- High Linearity. -111 dB of linearity measured for Vertical component, 107 dB for Horizontal (measured by USGS)
- Dynamic range exceeds 140 dB over the complete passband of the instrument (measured by USGS)
- Cross axis rejection better than 65 dB, Sensor axis orthogonal to better than 0.1 degrees
- Remote electronic mass locking and unlocking facility.
- Sensor can be operated with  $\pm 2.5$  degrees of tilt, and microprocessor controlled remote centering is provided.
- Adjustable feet.
- Special design adjustable feet which reduces spurious modes of resonance. Parasitic resonances are above 220 Hz.
- Low power consumption, 0.75 Watts. Operates over 10 to 30 Volt power input range.
- Stainless Steel Construction.



*CMG-3T  
Broadband Seismometer*

**One instrument CMG-3T can detect Earthtides, Earth Modes and have response up to 100 Hz**



The above plot shows Earthtides recorded by a 360s (0.0027Hz) CMG borehole seismometer. The data is raw 1 sps data taken from a CMG borehole seismometer with a downhole CMG-DM24 digitizer

CMG-3 Borehole Sensors have sufficient dynamic range, linearity and low self-noise to enable units to measure Earth Modes *-(ref: "The Needs for/of Low-Frequency Seismology – G. Laske" - Broadband Sensor Workshop*

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**Distributed By:-**



The CMG-3T seismometer is a compact three-component version of the CMG-3 broadband sensor. The sealed three-component stainless steel housing is suited for surface vault (observatory), subsurface vault and post hole installations.

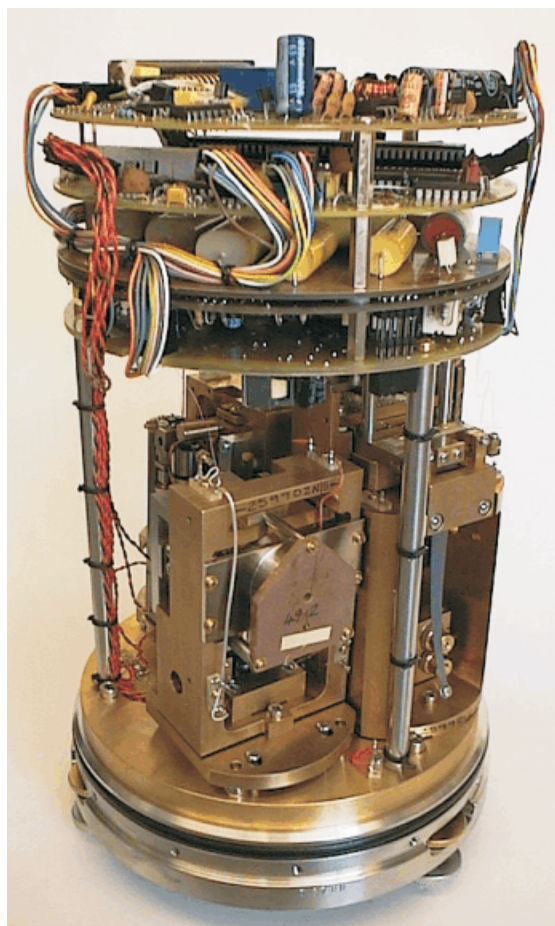
CMG-3T has been designed to provide seismic information over the COMPLETE seismic spectrum from very low frequencies up to 50 Hz. Various frequency response options are provided for the user and optionally the high frequency corner of the sensor response can be increased beyond 50 Hz.

These instruments do NOT require precise leveling of the sensor package to obtain long period mechanical response and can be used without leveling the sensor case up to  $\pm 2.5$  degrees of tilt.

The scope of the CMG-3T seismometer includes the associated peripheral equipment for borehole applications, including holelock, holelock installer and cable strain relief mechanism. Furthermore, CMG-3T can be installed inside ocean bottom capsules to be used as broadband ocean bottom seismometers.

### **MECHANICAL SYSTEM DESIGN**

The vertical and horizontal sensors are orthogonal to each other with an accuracy better than 0.1 degrees. The beam type sensor boom which defines the frame of reference in both the vertical and horizontal sensor are absolutely identical. The sensor boom with a displacement capacitive transducer and a constant flux feedback transducer are symmetrical.



The vertical sensor inertial mass and the inverted horizontal pendulum are both supported with leaf springs with a natural period of about 0.9 seconds. The beam type sensor boom moves with a single degree of freedom and the parasitic resonance of the complete sensor system is above 140 Hz.

The mechanical construction of the instrument is such that it is compact, rugged and easy to use. The mass clamping mechanism operates on the sensor mass and pushes the mass under controlled spring force with its prongs against the precisely machined cavities such as the mass is restrained to move in six degrees of freedom. The locking mechanism of the sensor mass ensures that under normal conditions, handling and transportation, the sensor pivots are not damaged.

The vertical component boom centering is accomplished by moving the end of the load bearing spring with a stable motorized precision micrometer under the control of microcontroller electronics. In the case of the horizontal sensor the centering is accomplished by tilting the sensor base, again with a stable motorized precision micrometer under the control of micro controller electronics.

The CMG-3T (three-component) sensors are housed within a completely 'O' ring sealed housing, and all the external components are manufactured from stainless steel.

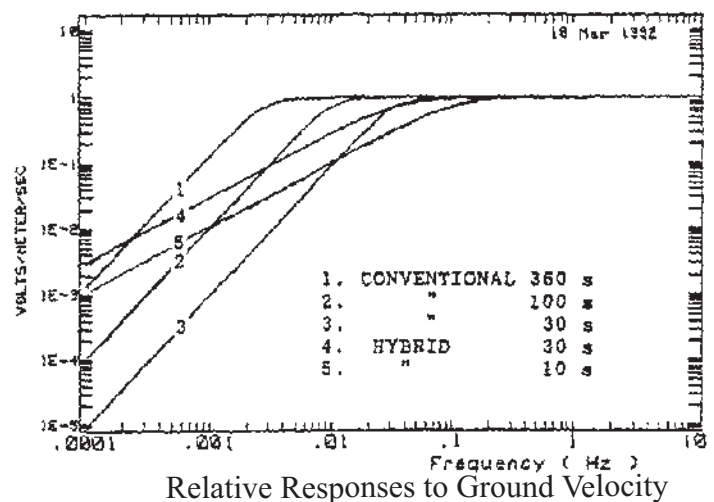
CMG-3T can also be delivered with a waterproof connector and cabling (see photo opposite). The waterproof connector/sensor can be immersed continuously under water down to a depth of 25 meters (other depth options are also available).



### FEEDBACK ELECTRONICS

In a practical broadband seismometer, the natural characteristics of the seismometer are never used. The period and damping of the sensor are completely deterred by a feedback loop which supplies a counter-force to the inertial mass sufficient to oppose any overall motion. The force required to restrain the movement of the mass is then a measure of the inertial force exerted by the mass due to ground motion. By using a suitable feedback network it is possible to obtain virtually any desired frequency response or system gain from a feedback seismometer. Ref 1, Ref 2.

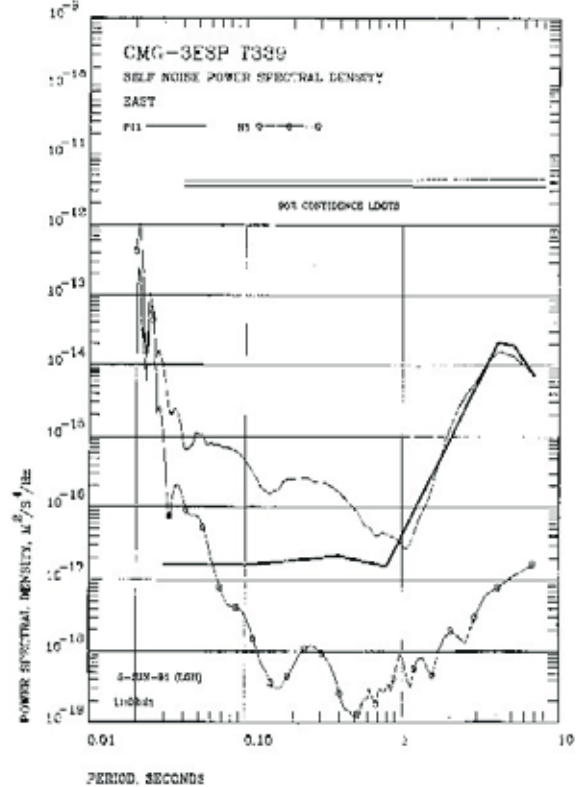
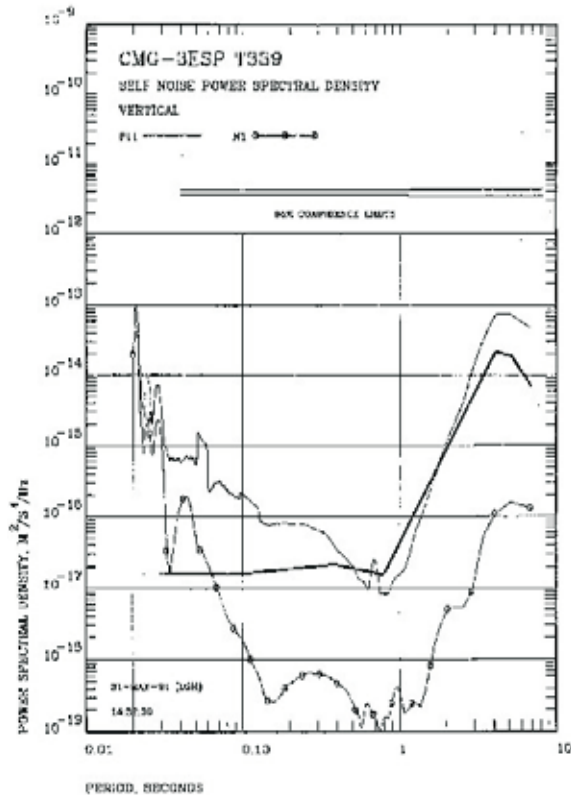
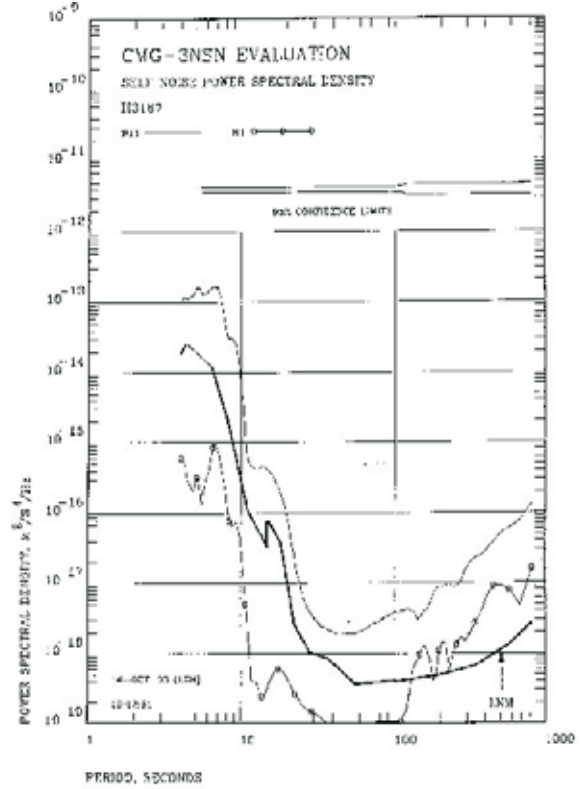
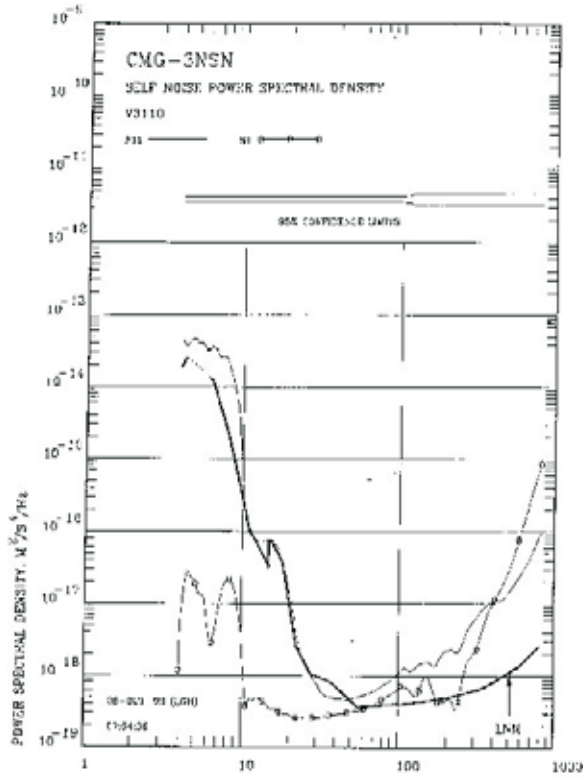
The figure opposite gives the comparative response of a conventional flat velocity output broadband sensor (direct from the feedback loop) and the optional hybrid response of the USGS National Seismic Network..



The family of curves shows the CMG-3T output response to input velocity in units of V/m/s. Curves 1, 2 and 3 are the conventional 360 second, 100 second and 30 second responses whilst curves 4 and 5 are the hybrid 10 second and 30 second (USGS NSN) responses.



The figures given below contain a typical estimate of the system noise power plotted as (small circled line) non-coherent power for vertical and horizontal sensors in the long period and short period bands separately. The power spectral estimates have been corrected for the system response and gain representing the sensor input power (continuous thin line) in units of acceleration. In these plots the Low Noise Model is plotted as the thick continuous line.





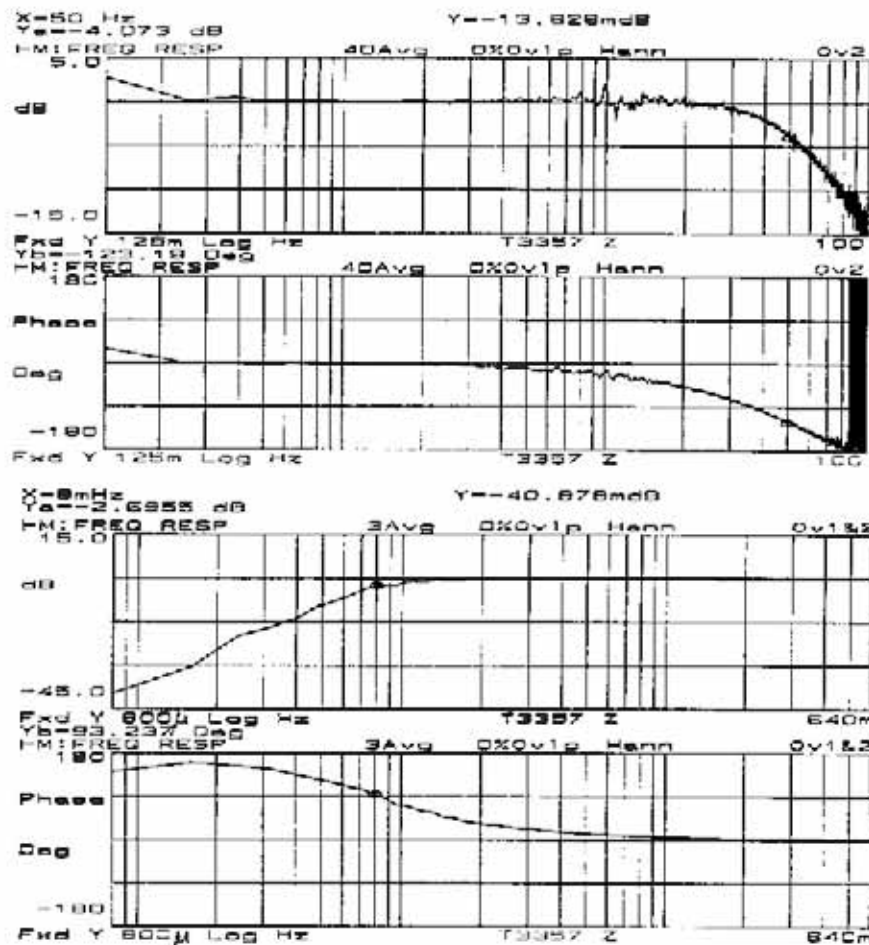
The theoretically calculated Brownian noise (Ref 1) of the sensor is set at -195 dB relative to 1 m<sup>2</sup>/s<sup>4</sup>/Hz of input ground acceleration. However, it is well known that the main practical problems in long period instruments arise from thermal, magnetic field, pressure effects in the mechanical system and more importantly the mechanical instability of the overall construction. In order to show the true practical noise estimates of the CMG-3 instrument, two identical sensor output signals are measured. The coherence function is used to estimate the signal power coherent between the two sensors and signal power non-coherent between the sensors which is considered to arise from the total inherent sensor noise.

Tests show that the CMG-3T noise estimates are below the Low Noise Model up to 18 Hz and down to 0.0125 Hz (80 seconds).

Please Note: CMG-3ESP type sensors results have been used as the high frequency noise estimates. The performance of CMG-3ESP and CMG-3T sensors are identical in the short period band (Ref 3). The CMG-3T has similar mechanical and electronic components to CMG-3NSN units which have been tested at Albuquerque Seismological Laboratory, USGS.

### SENSOR FREQUENCY RESPONSE

The CMG-3T seismometer is delivered with comprehensive documentation which includes the 'Operator's Guide' and complete calibration document. Each CMG-3T sensor measured frequency response is provided as normalized amplitude and phase plots. The frequency plots are given as the long period and short period sections of the seismic spectrum.



POLES AND ZERO TABLE	
WORKS ORDER NUMBER: 0436	
SENSOR SERIAL NO: T3356 and T3357	
POLES(HZ)	ZEROS(HZ)
$- 5.891 * 10^1 \pm 5.69 * 10^1$	0
- 31.5±33	0
- 145	
Normalising Factor: A = $3.01 * 10^1$	
Sensor Sensitivity: See Calibration Sheet	
NOTE: The above poles and zeros apply to the vertical and horizontal sensors and are given in units of Hz. To convert to Radians/sec multiply each pole or zero with 2π. The normalising factor A should also be recalculated.	

As well as the measured frequency response, poles and zeros of the sensor transfer function are provided as a single transfer function.

### WHY A SINGLE TRANSFER FUNCTION?

It is required that a modern broadband seismometer covers the complete seismic spectrum. Under no circumstances should the theoretical response of the sensor be described by dividing the response into separate bands as this methodology will simply turn the clocks back to the days when more than one seismometer (long period and short period) had to be used to cover the seismic spectrum.

### LINEARITY

The very wide dynamic range and the high linearity level of the CMG-3 sensor makes linearity measurement of the sensor system a challenging task. The linearity measurement of the CMG-3 sensor was carried out during the USGS NSN network sensor evaluation and the sensors exhibited distortion ratios of - 111 dB for the vertical and - 107 dB for the horizontal sensor. The linearity measurement method is given in Ref 3.

### REFERENCES

- Ref1 USHER, M.J., BURCH, R.F. and GURALP, C.M., “Wide-band Feedback Seismometers”, 1979. Physics of the Earth and Planetary Interiors, 18: 38-50.
- Ref2 GURALP, C.M., “The Design of a Three-component Borehole Seismometer”, 1980. Ph.D. Thesis, Univ of Reading.
- Ref3 Albuquerque Seismological Laboratory, NSN test data (unpublished).
- Ref4 USGS Report, “USGS Technical Summary”. 25 January, 1990.

## CMG-3T SEISMOMETER SYSTEM SPECIFICATION

### Outputs and Response

Full scale outputs:	± 20 Vdc differential velocity (2*750 V/m/s for 120 sec sensor) ± 10 Vdc mass position (3000 V/m/s <sup>2</sup> for 120 sec sensor)
Standard Response:	Flat velocity 0.0083 (120s) to 50 Hz
Optional USNSN Response:	Flat accel. 0.005 to 0.033 Hz; flat velocity 0.033 to 50 Hz
Other OPTIONAL Responses:	0.0333 (30s) to 50 Hz 0.0166 (60s) to 50 Hz 0.0100 (100s) to 50 Hz 0.0027 (360s) to 50 Hz Extend high frequency corner to 100 Hz.

### Controls

Calibration:	The calibration signal can be connected to each axis separately. Calibration enable lines are provided for each axis. Cal enable lines (active low) < 1mAmp.
Calibration Resistor	51K Ohm
Mass centering:	Microprocessor controlled. Automatic centering with remote Control.
Mass lock/unlock:	Microprocessor controlled with limit switches. Automatic mass lock/unlock with remote control.
Logic Level option:	Option to provide Sensor controlled from Active High logic

### Physical

Lowest spurious resonance:	140 Hz vertical
Temp. before recentre needed:	± 12 deg. C
Mass re-centering range:	± 2.5 deg from horizontal
Operating temperature range:	- 20 to + 75 deg C
Base plate and top cap:	Stainless steel
Pressure jacket material:	Stainless steel
Power/signal connector:	Milspec connector on top cap, KPT 02E-16-26P. Stainless, 1500 psi connector available.
Pressure relief valve:	On top cap
Carrying handle:	On top cap
Case diameter:	168 mm (6.61 in)
Case height with handle:	350 mm (13.75 in)
Weight:	31.4 lb (14.2 Kg)

### Power

Standard power supply:	+ 12 Vdc, with internal DC/DC converter(Isolated) (Can operate over 10 to 36 Volts.)
Current at standard (12 V) output:	+ 75 mA
Additional cal relay current:	< 1 mA
Additional current when re-centering:	+ 300 mA (See Operator's Guide.)